

$$a = \frac{2(\Delta d - v_i \Delta t)}{\Delta t^2}$$



$$\tau = Fr$$

$$a = \frac{2(\Delta d - v_i \Delta t)}{\Delta t^2}$$

$$I = \frac{V}{R}$$

$$t = \frac{W}{P}$$



$$\Delta p = v_i \Delta t + \frac{1}{2} a \Delta t^2$$

$$a = \frac{v_f - v_i}{\Delta t}$$

$$R = \frac{l}{V}$$

$$R = \frac{l}{V}$$



$$KE = \frac{1}{2} mv^2$$

$$t = \frac{W}{P}$$

$$F_{net} = ma$$

$$\Delta t = \frac{v_f - v_i}{a}$$



$$P = \frac{W}{t}$$

$$\Delta t = \frac{a}{v_f - v_i}$$

$$a_c = \frac{v_t^2}{r}$$

$$a = \frac{F_{net}}{m}$$



$$PE_g = mgh$$

$$d = \frac{W}{F}$$

$$d = \frac{F}{W}$$

$$r = \frac{v^2}{a}$$




$$W = Fd$$

$$r = \frac{a}{v^2}$$

$$a = \frac{m}{F_{net}}$$

$a = \sqrt{\frac{2KE}{m}}$

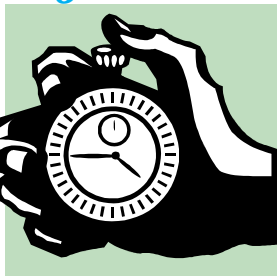


$x = \pm \sqrt{\frac{2PE}{k}}$

$Q = mc_p \Delta T$

$x = \pm \sqrt{\frac{k}{2PE}}$

$\Delta T = \frac{mc_p}{Q}$




$v = \frac{p}{m}$

$E = mc^2$

$\Delta T = \frac{mc_p}{Q}$

$c = \pm \sqrt{\frac{E}{m}}$




$f = \frac{v}{\lambda}$

$F = \frac{\Delta t}{J}$

$c = \pm \sqrt{\frac{m}{E}}$

$F = \frac{\tau}{r}$




$PE_{elastic} = \frac{1}{2} kx^2$

$E = Pt$

$F = \frac{\tau}{r}$

$t = \frac{p}{E}$




$p = mv$

$J = F\Delta t$

$v = \pm \sqrt{\frac{2KE}{m}}$

$F = \frac{J}{\Delta t}$



$\gamma f = a$

$h = \frac{PE_g}{mg}$

$h = \frac{mg}{PE_g}$